

HOMEWORK - #4 SOLUTIONS

$$\underline{2.5.6} \quad \begin{cases} \frac{\partial^2 v}{\partial x^2} = \frac{1}{\kappa} \frac{\partial v}{\partial t} + \gamma^2 v & 0 < x < a \\ v(0, t) = 0 & \frac{\partial v}{\partial x}(a, t) = 0 \\ v(x, 0) = T_0 \end{cases}$$

Steady State Solution

$$v_{xx} = \gamma^2 v$$

$$v(0) = 0 ; \quad v'(a) = 0$$

$$v(x) = c_1 e^{\gamma x} + c_2 e^{-\gamma x} \Rightarrow \text{Solution is } v(x) = 0$$

$$w(x, t) = v(x, t) - v(x)$$

$$\frac{\partial^2 w}{\partial x^2} = \frac{1}{\kappa} \frac{\partial w}{\partial t} + \gamma^2 w$$

$$w(0) = 0, \quad \frac{\partial w}{\partial x}(a) = 0$$

$$w(x, 0) = T_0$$

$$\phi''(x) T(t) = \frac{1}{\kappa} \phi(x) T'(t) + \gamma^2 \phi(x) T(t)$$

$$\phi(x) = c_1 \cos(\lambda x) + c_2 \sin(\lambda x)$$

$$\phi(0) = 0$$

$$\phi(a) = c_2 \frac{(2n-1)\pi}{2a} \cos\left(\frac{(2n-1)\pi}{2a} x\right)$$

$$\phi_n(x) = \sin\left(\frac{(2n-1)\pi}{2a} x\right)$$

$$T_n(t) = e^{-k(r^2 + \lambda_n^2)t}.$$

$$W(x,t) = \sum_{n=1}^{\infty} b_n \sin\left(\frac{(2n-1)\pi x}{2a}\right) e^{-k\left(r^2 + \left(\frac{2n-1}{2a}\right)^2\right)t}$$

$$b_n = \frac{2}{a} \int_0^a T_0 \sin\left(\frac{(2n-1)\pi x}{2a}\right) dx$$

$$= \frac{4T_0}{(2n-1)\pi}.$$

$$v(x,t) = \sum_{n=1}^{\infty} \frac{4T_0}{(2n-1)\pi} \sin\left(\frac{(2n-1)\pi x}{2a}\right) \cdot e^{-k\left(r^2 + \left(\frac{2n-1}{2a}\right)^2\right)t}$$

2.6.7

$$b_m = \frac{\int_0^a g(x) \sin(\lambda_m x) dx}{\int_0^a \sin^2(\lambda_m x) dx}$$

$$\begin{aligned} \int_0^a g(x) \sin(\lambda_m x) dx &= \left[-\cos(\lambda_m x) \frac{1}{\lambda_m} \right]_0^a \\ &= \frac{1}{\lambda_m} [1 - \cos(\lambda_m a)] \end{aligned}$$

$$\begin{aligned} \int_0^a \sin^2(\lambda_m x) dx &= \frac{1}{2} \left[x - \frac{\sin(2\lambda_m x)}{2\lambda_m} \right]_0^a \\ &= \frac{a}{2} - \frac{\sin(2\lambda_m a)}{4\lambda_m} \end{aligned}$$

$$b_m = \frac{2[1 - \cos(a\lambda_m)]}{\lambda_m \left[a - \frac{1}{2\lambda_m} \sin(2\lambda_m a) \right]}$$

2.7.1

$$\phi(x) = c_1 \cos(\lambda \ln(x)) + c_2 \sin(\lambda \ln(x)).$$

$$\phi(1) = 0 = c_1$$

$$\phi(2) = 0 \quad c_2 \sin(\lambda \ln(2)) = n\pi \rightarrow \lambda_1 = \frac{n\pi}{\ln(2)}$$

$$\phi_n(x) = \sin\left(\frac{n\pi}{\ln(2)} \ln(x)\right) \quad \text{where } \lambda_n$$

$$\int_1^2 \phi_n(x) \phi_m(x) \frac{1}{x} dx = \int_1^2 \sin(\lambda_n \ln(x)) \sin(\lambda_m \ln(x)) \frac{1}{x} dx.$$

$$= \frac{1}{2} \left[\frac{\sin(\lambda_n - \lambda_m) \ln(2)}{(\lambda_n - \lambda_m)} - \frac{\sin(\lambda_n + \lambda_m) \ln(2)}{(\lambda_n + \lambda_m)} \right]$$

$$= \underline{\underline{0}}$$

2.8.3

$$\begin{cases} (e^x \phi') + e^x r^2 \phi = 0 & 0 < x < a \\ \phi(0) = 0; \phi(a) = 0 \end{cases}$$

Verify $\phi_n(x) = e^{-x/2} \sin\left(\frac{n\pi x}{a}\right)$ with $r_n^2 = \left(\frac{n\pi}{a}\right)^2 + \frac{1}{4}$

Boundary Condition

$$\phi(0) = e^0 \sin(0) = 0$$

$$\phi(a) = e^{-a/2} \sin\left(\frac{n\pi a}{a}\right) = 0$$

eqn

$$\begin{aligned} (e^x \phi') + e^x r^2 \phi &= \left[e^x \left[\frac{n\pi}{a} e^{-x/2} \cos\left(\frac{n\pi x}{a}\right) - \frac{1}{2} e^{-x/2} \sin\left(\frac{n\pi x}{a}\right) \right] \right]' \\ &\quad + r^2 e^x e^{-x/2} \sin\left(\frac{n\pi x}{a}\right) = 0 \\ &= -\left(\left(\frac{n\pi}{a}\right)^2 + \frac{1}{4} - r^2\right) e^{x/2} \sin\left(\frac{n\pi x}{a}\right) = 0. \end{aligned}$$

Non trivial Solution is

$$r_n^2 = \left(\frac{n\pi}{a}\right)^2 + \frac{1}{4}$$

Let $f(x) = 1$ for $0 < x < a$

$$\begin{aligned} C_n &= \frac{\int_0^a f(x) \phi_n(x) \rho(x) dx}{\int_0^a \phi_n^2(x) \rho(x) dx} \\ &= \frac{\int_0^a e^{x/2} \sin\left(\frac{n\pi x}{a}\right) dx}{\int_0^a \sin^2\left(\frac{n\pi x}{a}\right) dx}. \end{aligned}$$

$$\int_0^a e^{x/2} \sin\left(\frac{n\pi x}{a}\right) dx = \left[e^{x/2} \left(-\frac{a}{n\pi} \cos\left(\frac{n\pi x}{a}\right) \right) \right]_0^a.$$

$$= \frac{\frac{a}{n\pi} \left[e^{\frac{a}{2}} \left[(-1)^{n+1} + 1 \right] \right]}{1 + \left(\frac{a}{2n\pi} \right)^2}$$

$$\int_0^a \sin^2\left(\frac{n\pi x}{a}\right) dx = \frac{a}{2}.$$

$$C_n = \frac{2n\pi \left[e^{a/2} (-1)^{n+1} + 1 \right]}{(n\pi)^2 + \frac{a^2}{4}}$$